

Efficient Robust Music Genre Classification with Depthwise Separable Convolutions and Source Separation

Gabriel Mersy

Department of Computer Science and Engineering, University of Minnesota
mersy006@umn.edu

Abstract

Given recent advances in deep music source separation, a feature representation method is proposed that combines source separation with a state-of-the-art representation learning technique that is suitably repurposed for computer audition (i.e. machine listening). A depthwise separable convolutional neural network is trained on a challenging electronic dance music (EDM) data set and its performance is compared to convolutional neural networks operating on both source separated and standard spectrograms. It is shown that source separation improves classification performance in a limited-data setting compared to the standard single spectrogram approach.

Introduction

One of the primary tasks of interest in the field of music information retrieval (MIR) is the classification of songs into genres. Many of the existing computer audition methods fail to account for small-scale features such as instrument rhythm or timbre. By uniting deep learning with music source separation, I delved into the problem of constructing a learner that can quickly discern characteristics that are necessary to the classification of music genres that have a high degree of similarity.

For the purpose of introducing the problem at hand, I conducted a simple empirical experiment on the GTZAN data set which is a traditional benchmark for music classification (Tzanetakis and Cook 2002). Consider two sets of music genres G_1, G_2 where $G_1 = G_2$. Let $g_1 S g_2, g_1 D g_2$ be two non-reflexive relations on these sets where the former depicts two acoustically *similar* genres, whereas the latter depicts two acoustically *different* genres. I constructed two binary classification tasks to examine performance differences between these two relations. It is clear that the network quickly reaches an accuracy of 100% on the task with heavy metal and jazz (difference relation D) but struggles to achieve comparable performance on the task with rock and country (accuracy of 27%; similarity relation S). Considering these results, with few data and little time, how might a learner compute salient features to discriminate between similar genres?

Copyright © 2021, Association for the Advancement of Artificial Intelligence (www.aaai.org). All rights reserved.

Related Work

Gjerdingen and Perrott show that human classification of music genre tends to occur within a quarter of a second and that listeners are able to distinguish one genre from another based on a decoding of the song components (Gjerdingen and Perrott 2008). Existing genre classification methods by means of source separation tend to focus on a limited number of sources (e.g. percussive and harmonic) and employ unsupervised techniques such as non-negative matrix factorization to separate the tracks (Rosner and Kostek 2018).

Methods

Data set and music segmentation Five genres from the the GiantSteps+ EDM Key Data set were included, and these genres were combined with an additional genre from a set of free download songs¹ for a total of *66 songs* spanning *six genres* (Knees, Faraldo et al. 2015). These genres are all closely related which by the logic of the introductory GTZAN experiment should present a challenging classification task. A human interactive technique was employed to segment each song. The length of each audio segment was then trimmed to approximately 10 seconds at a sample rate of 22,050 hertz.

Feature representation To obtain the feature representation, a U-net model was used to divide each stereo audio signal $\mathbf{X}(t)$ into its musical constituents such that

$$\mathbf{X}(t) = \tilde{\mathbf{S}}_b(t) + \tilde{\mathbf{S}}_d(t) + \tilde{\mathbf{S}}_o(t) + \tilde{\mathbf{S}}_v(t) \quad (1)$$

where $\tilde{\mathbf{S}}_i(t) \in I$ represents the estimated audio sources in the set of instruments I : bass, drums, other, and vocals respectively (Hennequin et al. 2019). Each stereo instrument $\tilde{\mathbf{S}}_i(t)$ in (1) was replaced with a mono mel spectrogram $\tilde{\mathbf{M}}_i \in I$ that captures the spectral frequency response. By stacking each spectrogram depthwise, a feature representation that is analogous to a color image was derived—where each channel is composed of an instrument source spectrogram corresponding to one of three instrument types (vocals were not included). The feature tensor for the source separated representation has the shape (66, 128, 458, 3). Two feature tensors with the shape (66, 128, 458, 1) were computed for the purpose of comparison to baseline methods—only one of which included vocals.

¹u/Futureops 2017; Free download collection... *Reddit*.

Neural networks The four neural networks that I implemented were composed of two convolution layers each followed by a max pooling layer. Class weights were added to attenuate the unbalanced nature of the data set. Two of these models operated on the source separated tensor: standard 2D multichannel convolution and 2D depthwise separable convolution. One standard single-spectrogram network operated on the tensor that includes vocals, while the other network operated on the tensor that does not include vocals.

In contrast to multichannel 2D convolution which convolves a 3D filter $\mathcal{W} \in \mathbb{R}^3$ over the image channels of \mathcal{Y} , 2D depthwise separable convolution applies an identical filter $\mathbf{W}_d \in \mathbb{R}^2$ to each of the c channels separately to produce c feature maps. As seen in (2), these feature maps are then combined with a pointwise $1 \times 1 \times c$ convolution filter \mathcal{W}_p (Kaiser, Gomez, and Chollet 2018).

$$\text{SepConv}(\mathcal{W}_p, \mathbf{W}_d, \mathcal{Y}) = \text{PointwiseConv}_{(i,j)}(\mathcal{W}_p, \text{DepthwiseConv}_{(i,j)}(\mathbf{W}_d, \mathcal{Y})) \quad (2)$$

With $c = 3$ channels and a receptive field size of k , for any $k > 1$ depthwise separable convolution reduces the number of parameters per convolution from $9k$ to $3k + 9$ thereby proportionately reducing computation time. Given that a small sample size generally results in parameter gradients that have high variance, architectural techniques were implemented to increase model bias. Network parameters were regularized with penalties on both the L1 and L2 norms, batch normalization was applied after each convolution layer, and a dropout layer with $p = 0.5$ was introduced immediately prior to the fully connected layer.

Model evaluation To improve the validity of the experiments, two metrics were introduced that are based on the sampling distributions of model accuracy and F1 across multiple trials. For each independent trial, 80% train-20% test splits were carried out at a unique random seed to produce identical train and tests sets for each model. The models were then trained for six epochs using sparse categorical crossentropy loss, and metrics were recorded for the epoch with the minimum test loss. The mean for each metric after 50 trials is reported in Table 1. The F1 distributions for the 3 and 1 spectrogram models after 50 trials are presented in Figure 1.

Model	Accuracy	F1
1 spec, 2DConv-Full	0.380	0.350
1 spec, 2DConv-No-Vox†	0.384	0.371
3 spec, 2DConv	0.456	0.435
3 spec, DW-2DConv	0.451	0.419

Table 1: Mean test set metrics for 50 trials; †baseline

Conclusion

Each of the source separated 3 spectrogram models significantly outperformed the 1 spectrogram baseline. The 3 spectrogram 2D convolution model marginally outperformed the depthwise convolution model when each was compared to

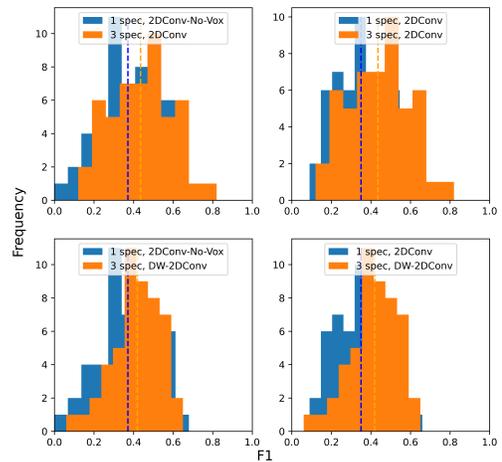


Figure 1: F1 scores of 3 spectrogram (orange) and 1 spectrogram (blue) models; dashed line denotes the mean

the baseline (F1 p-values of $p = 0.04$ and $p = 0.07$ respectively). The underperformance of the depthwise model is best understood by its left-skewed F1 distribution, which is markedly different from the Gaussian F1 distribution of the 2D convolution model. This instability could be elucidated by the depthwise model’s reduced parameter quantity. It is also observed that the inclusion of vocals had little effect on classifier performance in this setting. Ultimately, two songs from the same genre presumably have paired instrument channels that have similar temporal and spectral patterns, while this may not be case for two songs from different genres. Thus, it is likely that the improved performance of the 3 spectrogram models can be attributed to information gained from the introduction of source separation methods.

References

- Gjerdingen, R. O.; and Perrott, D. 2008. Scanning the Dial: The Rapid Recognition of Music Genres. *Journal of New Music Research* 37(2): 93–100.
- Hennequin, R.; Khelif, A.; Voituret, F.; and Moussallam, M. 2019. Spleeter: a Fast and State-of-the-Art Music Source Separation Tool with Pre-trained Models. In *Proceedings of ISMIR 2019*.
- Kaiser, L.; Gomez, A. N.; and Chollet, F. 2018. Depthwise Separable Convolutions for Neural Machine Translation. *ICLR 2018* abs/1706.03059.
- Knees, P.; Faraldo, Á.; et al. 2015. Two Data Sets for Tempo Estimation and Key Detection in Electronic Dance Music Annotated from User Corrections. In *Proceedings of ISMIR 2015*.
- Rosner, A.; and Kostek, B. 2018. Automatic Music Genre Classification Based on Musical Instrument Track Separation. *J. Intell. Inf. Syst.* 50(2): 363–384.
- Tzanetakis, G.; and Cook, P. 2002. Musical genre classification of audio signals. *IEEE Transactions on Speech and Audio Processing* 10(5): 293–302.